# AK-ST7FMC Quickstart Tutorial



### Jumper Settings and Connections for the Provided AMETEK BLDC Motor



Jumper	Position			
S1	"< 35V ONLY" <sup>(*)</sup>			
W3	Present			
W4	Present			
W5	Present			
W6	Not Present			
W7	Not Present			
W8	Not Present			
W9	Not Present			
W10	Lower position			
W11				
W12	"VARIABLE"			
W13	Not Present			
W14				
W15	Sensoriess mode (default): all jumpers in upper position Sensor mode: all jumpers in lower position			
W16				
J8	No jumper present			
J9	All jumpers present			
J10	No jumper present			
J15	All jumpers present			

(\*) Note: when using a BLDC motor that requires < 18 V DC, remove the S1 jumper. When using a BLDC motor that requires > 35 V DC, set the S1 jumper to the "HIGH VOLTAGE" position.

### **Typical Jumper Settings and Connections for a Generic AC Motor**



Jumper	Position		
S1	"<35V ONLY" or "HIGH VOLTAGE"		
W3	Present		
W4	Present		
W5	Present		
W6	Not present		
W7	Not present		
W8	Not present		
W9	Not present		
W10	Lower position		
W11			
W12	"VARIABLE"		
W13	Present		
W14	Lower position		
W15			
W16	Not present		
8L	All jumpers present		
J9	All jumpers present		
J10	No jumper present		
J15	All jumpers present		



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# **AK-ST7FMC** Quickstart Tutorial



#### Start Working in Minutes!



This Quickstart Tutorial has been designed to get you started with the AK-ST7FMC Starter Kit. You will setup the instrument and run the provided BLDC motor in minutes.

#### **Safety Warnings**

The AK-ST7FMC Starter Kit should only be used by engineers and technicians who are experienced in power electronics.

> Before supplying the board, double check proper connections, make sure that there are no metal parts on, below or around the PCB and that there are no undesired earth/ground loops due to measuring equipment such as an oscilloscope.

### Install the Software

The AK-ST7FMC System Software setup program is located on the SofTec Microsystems "System Software" CD-ROM provided with the instrument. The setup program will copy the required files (including the USB driver) to your hard drive.





### **Connect in DART-STX** to the Motor System







Found New Hardware Wizard

The first time inDART-STX is connected to the PC, Windows recognizes the instrument and starts the "Found New Hardware Wizard" procedure, asking you to specify the drivers to use for the instrument.

The procedure is slightly different on each version of Windows. On Windows XP, select the **"Install the software automatically"** option and click on the "Next" button.

Be sure not to specify any drive or optional location where to look for the driver, since it has already been installed on your hard disk by the AK-ST7FMC Control Panel setup.



Note: both Windows 2000 and Windows XP may issue a warning during the "Found New Hardware" Wizard" procedure. This warning is related to the fact that the USB driver used by inDART-STX is not digitally signed by Microsoft, and Windows considers it to be potentially malfunctioning or dangerous for the system. However, you can safely ignore the warning, since every kind of *compatibility/security test has* been carried out by SofTec Microsystems.

#### **Power Up the Motor Control Board**

Power up the Motor Control board by connecting the output terminals of your DC power supply to the "MAINS" connector. The provided voltage must be 24 V DC and your power supply must be able to provide a current of 4 A. Polarity is not important. The board's power LED will turn on.





#### Run the AK-ST7FMC **Control Panel**



A Control Panel application is provided which allows you to change (in real time) all of the motor's electrical parameters. In this way it is possible to learn all of the features offered by the ST7FMC integrated motor control peripheral. To start the AK-ST7FMC Control Panel, select **Start > SofTec** Microsystems > AK-ST7FMC > AK-ST7FMC Control Panel.

The AK-ST7FMC Control Panel will ask you what kind of motor you are using (1). Make sure that the **"3 Phase Brushless Permanent Magnet AC or DC** Motor (Trapeziodal)" option is selected and click the "OK" button.

The AK-ST7FMC Control Panel main window will open (2).



**AK-ST7FMC Control** Panel: First Steps (1/2)

Change the **"Speed Regulation"** parameter to **"Closed Loop"** (1) and click

the "START" button (2). A firmware will be automatically created based on all of the Control Panel's parameter and downloaded to the ST7FMC microcontroller in the Motor Control board.

At the end of the download phase the motor will start to run.





Click the "STOP" button (2) to stop the motor.







You have successfully completed this tutorial! You can now continue to experiment with the AK-ST7FMC Control Panel on your own.

Additionally, you can develop and debug your own application by installing the **"inDART-STX for ST7"** software (which includes a complete development toolchain) present on the SofTec Microsystems "System Software" CD-ROM.

		Main Motor Settings
Motor Type  AMETEK Motor  Other BLPMDC Motor	Poles pairs	Detection Mode         Driving Mode         Speed Regulat                © Sensor120°               © Current               © Open Loop               © Open Loop               © Closed Loo               © Closed Loo               © Closed Loo
		Start-In Settings
Alignment phase		Acceleration phase
Final Current	2 🗢 A	Mechanical Acceleration Rate 1500 🗢 Rpm /s
Final Duty Cycle	70 🔷 %	
Alignment Duration	1250 <b>1</b> ms	Duty Lycle 70 💌 %
Alignment Daradon	1200	Current 2 A
		Number of Z events before 2 - Frequency 32.5 H
	→Time	Step number without Z detection 2 🗲 Total Duration 653 ms
		Beal-Time Settings
Settings     2001       Target Mechanical     2001       Speed     70       Duty Cycle     70       Current Reference     1.5       Delay Coefficient     8-emf rising edge     20       B-emf falling edge     20		Closed Loop Parameters       Proportional Coefficient (Ki)       20       Proportional Coefficient (Ki)       20       Integral Coefficient (Ki)       20       Integral Coefficient (Kii)       20       20       20       20       20       20       20       20 </td
Change Motor Type	D	efault Settings d Settings Generate Source Files

Motor Type AMETEK Motor Other BLPMDC Motor	Main Mo es pairs Detection Mode C Sensorless C Sensor 120' C Sensor 120'	tor Settings Driving Mode © Current © Voltage	Current Limitation 0.2	Speed Regulation C Open Loop 2 \$ A C Closed Loop
	Start-U	p Settings		
Alignment phase	Acceleration phase			
Final Current 2	A Mechanical Acce	eration Rate 15	00 🚖 Rpm /s	
Final Duty Cycle 70	Duty Cycle	70	\$ %	
Alignment Duration 12	50 🚖 ms Current	2	₹ A Val	ues at end of ramp
Current	Number of Z ever	its before		ectrical 32.5 Hz
	auto-switched mo	de l		atal Duration 653 mo
	→Time Step number with	out∠detection	<b>_</b>	
		ne Settings		
Settings Target Mechanical Speed Duty Cycle Current Reference 1.5	Rpm Closed Loop Parameters     Z Integral Coefficient (Ki)     Proportional Coefficient (	20 Koj 20	Feedback Electrical Frequency 168.4 Hz	Power Stage Status
Dolau Coofficient	ampling Time	30 ms	Reported Current Limit	Bus Over-Voltage
Biemfirising edge 20			1.44 A	Motor Status
	STOP .	1		Start-up Fails
B-emffalling edge   <sup>20</sup> 主	/256			I Motor Stalled
Change Motor Type	Default Settings	$\gamma_{2}$	ettings	Generate Source Files

P	lease also read carefully all of the AK-ST7FMC
C	locumentation.

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